EECE 478:
Computer Graphics
Vision and Viewing
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UBC Dept. of ECE

## Learning Objectives

- Real-world optics
- Describe how images are formed by light in the world
- Describe the roles of the eye, lens and retina in forming images
- Simulated optics
- Define a pinhole/synthetic camera model
- Define the simplifications made in the simple camera model used by OpenGL
- Describe the internal and external camera parameters


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- Modelling and Rendering
- Describe how a 3D model is rendered to the screen
- Describe the stages of a typical 3D graphics pipeline

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| Vocabulary |  |
| - Image | UBC Dept. of ECE |
| - Viewer | - Pinhole camera |
| - View | - Cenection |
| - Viewing geometry | - Field of view |
| - Eye | - Focal length |
| - Retina | - Projection plane |
| - Lens | - Clipping |
| - Light field |  |
|  |  |

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- Image
- Pinhole camera
- View
- Centre of projection
- Viewing geometry
- Focal length
- Retina
- Projection plane
- Lens
- Light source

Vocabulary

- 3D Model
- Rendering
- Pixel
- Graphics pipeline
- Scene geometry
- Projection
- Rasterization $\qquad$
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## The Eye

Iris

- Restricts amount of light entering eye

Lens

- Focuses light rays onto retina

Retina

- Surface on which image is formed
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Pinhole Camera Model
Simplifications:
- All rays pass through single point (pinhole)
- No lens (all rays are straight)
- Imaging surface is plane (imaging plane)
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## Synthetic Camera Model

1. Viewer (camera) is defined separately from objects
2. Image computed with simple projective geometry

- Project all object points through centre of projection onto projection plane
- Image is rectangular subset of projection plane. Points that project outside of image are clipped


## Clipping

- Projection plane is limited in size
- If point projects outside of image it is not displayed (clipped)
- w/h is aspect ratio
- $\theta$ is field of view

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