## Solutions to Assignment 1

## Question 1

| decimal | binary | hex |
| ---: | ---: | ---: |
| 8 | 1000 | $0 \times 8$ |
| 7 | 0111 | $0 \times 7$ |
| 16 | 10000 | $0 \times 10$ |
| 15 | 1111 | $0 x f$ |
| 256 | 100000000 | $0 x 100$ |
| 255 | 11111111 | $0 x f f$ |
| 237 | 11101101 | $0 x E d$ |

## Question 2

| binary | hex | decimal |
| ---: | ---: | ---: |
| 1011 | 0x0b | 11 |
| 10111011 | $0 x b b$ | 187 |
| 10000000 | $0 \times 80$ | 128 |
| 111100 | $0 \times 3 \mathrm{c}$ | 60 |
| 00111100 | $0 x 3 \mathrm{c}$ | 60 |

## Question 3

| hex | binary | decimal |
| ---: | ---: | ---: |
| 0x0e | 00001110 | 15 |
| 0xe | 00001110 | 15 |
| 0xAA | 10101010 | 170 |
| 0xFA | 11111010 | 250 |
| 0x40 | 01000000 | 64 |
| 0x18 | 00011000 | 24 |

## Question 4

1. A bitwise 'and' operation with a ' 1 ' bit retains the value of that bit. A bitwise 'and' operation with a ' 0 ' bit always sets that bit to ' 0 '.
```
    ( 0xaa & Ox0f )
= 0x0a
```

```
2. ( 0x3c & 0xf0 ) | ( 0x3c & 0x0f )
    =( 0x30 ) | ( 0x0c )
    = 0x3c
```

/* Print the binary value of an integer less than 32768 . We start at the largest applicable power of 2 and work our way down to the smallest power of 2. For each power, if that power is "contained" in the number we remove it and print a '1', otherwise we print a '0'. When all powers have been tested the result is that we have printed the binary representation of the number. */
\#include <stdio.h>

```
void printbin ( int n )
{
    int p ;
    p = 16384;
    while ( p >= 1 ) {
        if ( n >= p ) {
            n = n - p;
            printf ( "1" ) ;
        } else {
                printf ( "0" ) ;
        }
        p = p / 2;
    }
    printf ( "\n" ) ;
}
```


## Question 6

This solution uses an index variable n which is also used to count the number of characters preceeding the terminating zero (null) character.

```
int len ( char s[] )
{
    int n ;
    n = 0;
    while (s[n] != 0 ) {
        n = n + 1 ;
    }
    return n ;
}
```


## Question 7

Using the labels given in the diagram the inputs are: obs (obstruction detected), up, down,top, and bottom. The outputs are: raise, and lower.

There are 3 combinations of outputs: (1) the "raise" motor turned on, (2) the "lower" motor turned on, and (3) neither motor turned on. The controller must therefore have at least 3 states. We will assign these states the labels U, D, and S, respectively. We will attempt to produce a correct design with this many states and add additional states if required to meet the specifications. The outputs for each state are thus:

| state | raise | lower |
| :---: | :---: | :---: |
| U | 1 | 0 |
| D | 0 | 1 |
| S | 0 | 0 |

Comparing the outputs required for each state and the state encoding, we see that both tables are the same so the output equations are: $U=A$ and $D=B$.

A simple state transition diagram would be as follows:


The diagram above (like the question itself) is ambiguous because the logical expressions for various state transitions are not mutually exclusive. For example, it is not clear what should happen if both the up and down inputs are ' 1 '. These ambiguities need to be resolved before a controller can be implemented. The following state transition table unambiguously gives the transitions which are taken for each input condition. The symbol ' X ' is used as the "don't care" value indicating that the same transition takes place regardless of the value of that particular input.

The tables below were prepared by assuming that the controller obeys the inputs in the following order of priority: obstruction, the expected limit switch in (top/bottom), and direction buttons (up/down). If both buttons are pressed simultaneously the door reverses direction.

A row containing $N$ ' X 's is equivalent to $2^{N}$ rows with the 'X's replaced with the $2^{N}$ combinations of 1 's and 0 's. A quick check is to make sure that if there are $N_{\text {in }}$ inputs the sum of the $2^{N} \mathrm{~s}$ is $2^{N_{\mathrm{in}}}$.

| current state | inputconditions |  |  |  |  | next <br> state |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | obs | up | down | top | bottom |  |
| D | 1 | X | X | X | X | U |
| D | 0 | X | X | X | 1 | S |
| D | 0 | 0 | X | X | 0 | D |
| D | 0 | 1 | X | X | 0 | U |
| S | 1 | X | X | X | X | U |
| S | 0 | 0 | 0 | X | X | S |
| S | 0 | 0 | 1 | X | X | D |
| S | 0 | 1 | 0 | X | X | U |
| S | 0 | 1 | 1 | X | X | S |
| U | 1 | X | X | X | X | U |
| U | 0 | X | X | 1 | X | S |
| U | 0 | X | 0 | 0 | X | U |
| U |  | X | 1 | 0 | X | D |

Note that in each state there is exactly one row (transition) that matches (would happen) any possible pattern (input). Anything else would be an ambiguous specification.

We'll use $A$ and $B$ as the state variables. We'll use the following state encoding (others are also possible):

| state | $A$ | $B$ |
| :---: | :---: | :---: |
| U | 1 | 0 |
| D | 0 | 1 |
| S | 0 | 0 |

The state transition table can be re-written using these encoding as:

| current <br> state | input <br> conditions |  |  |  |  |  |  | next <br> state |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $A$ | $B$ | obs | up | down | top | bottom | $A^{\prime}$ | $B^{\prime}$ |  |
| 0 | 1 | 1 | X | X | X | X | 1 | 0 |  |
| 0 | 1 | 0 | X | X | X | 1 | 0 | 0 |  |
| 0 | 1 | 0 | 0 | X | X | 0 | 0 | 1 |  |
| 0 | 1 | 0 | 1 | X | X | 0 | 1 | 0 |  |
| 0 | 0 | 1 | X | X | X | X | 1 | 0 |  |
| 0 | 0 | 0 | 0 | 0 | X | X | 0 | 0 |  |
| 0 | 0 | 0 | 0 | 1 | X | X | 0 | 1 |  |
| 0 | 0 | 0 | 1 | 0 | X | X | 1 | 0 |  |
| 0 | 0 | 0 | 1 | 1 | X | X | 0 | 0 |  |
| 1 | 0 | 1 | X | X | X | X | 1 | 0 |  |
| 1 | 0 | 0 | X | X | 1 | X | 0 | 0 |  |
| 1 | 0 | 0 | X | 0 | 0 | X | 1 | 0 |  |
| 1 | 0 | 0 | X | 1 | 0 | X | 0 | 1 |  |

I'll use the boolean variables $o, u, d, t$, and $b$ for obs, up, down, top, and bottom respectively.

The next-state equations are:

$$
\begin{aligned}
A^{\prime}= & \bar{A} B o+\bar{A} B \bar{o} u \bar{b}+ \\
& \overline{A B} o+\bar{A} \bar{B} \bar{o} u \bar{d}+ \\
& A \bar{B} o+A \bar{B} \bar{o} \bar{d} \bar{t} \\
& \\
B^{\prime}= & \bar{A} B \overline{o u} \bar{b}+ \\
& \overline{A B} \bar{o} \bar{u} d+ \\
& A \bar{B} \bar{o} d \bar{t}
\end{aligned}
$$

The schematic is:


## Question 8

The controller inputs are the coin detector outputs (labelled $X$ and $Y$ ). The controller output is the candy release signal (labelled $R$ ). The four states correspond to the possible sum of money deposited: 0 , $5 \mathrm{c}, 10 \mathrm{c}$, and 15 c . The state transition diagram is:


The release is only turned on when the count of money reaches 15 cents. Tabular descriptions of the state transitions and outputs are:


