

# The Effect upon Channel Capacity in Wireless Communications of Perfect and Imperfect Knowledge of the Channel

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Reading Group Discussion

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## Intro ./ Overview

- ▶ Time Variation, ISI and multiple access dealt with an error in channel est. perspective.
- ▶ The general idea is to establish bounds for the asymptotic performance with imperfections in CSI.
- ▶ Look at Mutual Info. Use of Gaussian codebooks.. hence looking at capacity ?
- ▶ Use perturbation to model error in CSI - Error with known variance.
- ▶ Will focus on the uplink case . . . and start by looking at the mutual info for a known channel.
- ▶ **General Trick: Upper bound the mutual info. with that of an equal variance Gaussian process**



# Perfectly Known Channel

## Channel Model

- ▶ Imp. Resp. at  $t' - t$ :

$$g(t', t) = \sum g_m(t', t) = \sum a^m(t') \delta(\tau^m(t') - t)$$

where  $\tau^m(t) = \tau^m + (B^m/f_o)t$ .

- ▶ Discrete Time Model:  $y[k] = \sum_{\text{all paths } l} \sum_l s[k-l] g^m[k, l] + n[k]$

## Max. Mutual Info. – Complex Transmission (Single User)

- ▶ Mutual Info. given by  $I(\underline{Y}_k; \underline{S}_k) = h(\underline{Y}_k) - h(\underline{N}_k)$
- ▶ Eqn.(12) - approx. assumption of time and BW limiting - ???
- ▶ Using sampling rate assumptions construct  $\underline{f}_{2k'}$ .
- ▶ Using W.filling Max MI =  $\frac{1}{2T} \sum_{i=1}^{2k'} \ln \left( 1 + \frac{u_i \lambda_i}{WN_0/2} \right)$



# Multiple Users- Non-cooperating case

## Mutual Info

- ▶ The case where the antennas cooperate  $\rightarrow$  antenna array (development similar to single user).
- ▶ Maximise  $I(\{\underline{\mathbf{S}}_{i_{2k'}}\}_{i=1}^K; \underline{\mathbf{Y}}_{2k}) = h(\underline{\mathbf{Y}}_{2k}) - h(\underline{\mathbf{N}}_{2k})$   
(each source has individual power constraints - sum of all M.I / time)
- ▶  $h(\underline{\mathbf{Y}}_{2k})$  is maximized by using Gaussian inputs.

## 2-user case

- ▶ Maximize (Typo in eqn. 23)  
$$\max \ln \left( |\mathbf{f}_1^{2k} \underline{\Lambda}_{\mathbf{S}_1} \mathbf{f}_1^{2k^T} + \mathbf{f}_2^{2k} \underline{\Lambda}_{\mathbf{S}_2} \mathbf{f}_2^{2k^T} + \underline{\Lambda}_{\mathbf{N}_{2k}}| \right)$$
- ▶ The above region is proved to be convex.. hence maximization  $\rightarrow$  global max.



# Effect of Channel Error of Known Variance

## Assumptions on channel

- ▶ Unknown at Tx.
- ▶ Partially known at Rx.
- ▶ **Idea**: Look at *asymptotic* variations of the channel.

## Mutual Info.

- ▶  $\underline{Y} = \underline{F}\underline{S} + \underline{N}$ .

▶

$$I(\underline{Y}; \underline{S}) = h(\underline{S}) - h(\underline{S}|\underline{Y}) \quad (1)$$

- ▶ Known Channel:

$$I(\underline{Y}; \underline{S}|\underline{F}) = h(\underline{S}|\underline{F}) - h(\underline{S}|\underline{Y}, \underline{F}) \quad (2)$$

- ▶ Eqn.2 - Eqn.1 gives (typo in Eqn.34)

$$I(\underline{Y}; \underline{S}|\underline{F}) - I(\underline{Y}; \underline{S}) = I(\underline{S}; \underline{F}|\underline{Y}) \quad (3)$$



## Single User - cont'd (single symbol)

- ▶ Channel known within some MSE.
- ▶ Therefore  $F = \bar{F} + \tilde{F} \dots$  where  $\tilde{F}$  accounts for the meas. error.
- ▶ Recall  $I(Y; S) = h(Y) - h(Y|S)$  and from  $Y = S\bar{F} + S\tilde{F} + N$  we have

$$h(Y|S = s) = h(s\tilde{F} + N) \quad (4)$$

- ▶ Integrating over dist. of  $\tilde{F}$

## Lower Bound on MI using the worst case dist. under a cov. constraint

- ▶ Max.  $I(Y; S) = h(S) - h(S|Y) \dots$  Use Gaussian dist.  $S$  - might not be max.
- ▶ Max  $h(S|Y) \dots$  thus yielding lower bound on  $I$ .

$$h(S|Y) \leq \frac{1}{2} \ln(2\pi e \text{Var}(S - \alpha Y)) \quad (5)$$



## .. and this is the part I dont understand very well

### lower bound

- ▶  $\alpha = \frac{E[SY]}{E[Y^2]} = \frac{\bar{F}\sigma_s^2}{\bar{F}^2\sigma_s^2 + \sigma_F^2\sigma_s^2 + \sigma_N^2}$
- ▶ Use above to get  $\text{Var}(S - \alpha Y)$  and hence lower bound on  $I(S; Y)$

### Upper bound

- ▶ For upper bound use the fact  $I(S; Y) \leq I(S; Y|F)$  and then Jensen's ineq. to get Eqn.(49).
- ▶ Loss in mutual info. due to uncertainty about the channel

$$I(S; Y|F) - I(S; Y) \leq \frac{1}{2} \ln \left( 1 + \frac{\sigma_F^2 \sigma_S^2}{\sigma_N^2} \right) \quad (6)$$

### Interpretation

- ▶ Upper bound : Meas. noise = Extra Tx power
- ▶ Lower bound : Not useful at all
- ▶ Not discussing the extension to multiple symbols but (Interpretations are the same) ..

Ques. why does a matrix have to be invertible if its white (pg. 940). ▶



# Multiple Access Case

## Channel Assumptions and idea

- ▶ Channels of different users are mutually independent.
- ▶ If user  $k$  can be decoded  $\rightarrow$  interference from this user be cancelled with error owing to channel est. errors.

## Mutual Info. (2 user case)

- ▶ Assumption: All Rx components part of signal ... Therefore you get upper bound on mutual info.
- ▶  $I(Y; S_1 | S_2) \leq I(Y; S_1 | S_2, F_1, F_2) = h(Y | S_2, F_1, F_2) - h(N)$
- ▶ Again upper bounded using Gaussian dist.

$$\begin{aligned} I(Y; S_1 | S_2) &\leq \frac{1}{2} E_{F_1} [\ln(\sigma_N^2 + \sigma_{S_1}^2 F_1^2)] - \frac{1}{2} \ln(\sigma_N^2) \\ &\leq \frac{1}{2} \ln \left( 1 + \frac{\sigma_{S_1}^2 F_1^2}{\sigma_N^2} \right) \end{aligned}$$





## Lower bound



$$\begin{aligned} I(Y; \mathbf{S}_1 | \mathbf{S}_2) &= h(\mathbf{S}_1 | \mathbf{S}_2) - h(\mathbf{S}_1 | Y, \mathbf{S}_2) \\ &= h(\mathbf{S}_1) - h(\mathbf{S}_1 | Y, \mathbf{S}_2) \\ &= h(\mathbf{S}_1) - h(\mathbf{S}_1 | (Y - \bar{F}_2 \mathbf{S}_2), \mathbf{S}_2) \\ &\geq h(\mathbf{S}_1) - h(\mathbf{S}_1 | (Y - \bar{F}_2 \mathbf{S}_2)) \end{aligned}$$

- ▶ ... and then use the LMMSE estimate

## Interpretation

- ▶ Main Result : Uncertainty of channel of other users while doing Interference cancellation - lower bounded by more AWGN.
- ▶ Fig. 6 reinstates the widely known result that interference cancellation is better than treating the MAC as an interference channel.

